

A study on hypersurface of complex space form

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ABSTRACT. We show that quasi-umbilical, generalized quasi-umbilical, super quasi-umbilical hypersurfaces of a complex space form are quasi-Einstein, mixed generalized quasi-Einstein and mixed super quasi-Einstein manifolds, respectively. We also prove that a Bochner flat space of generalized complex space form is an Einstein manifold.

1. Introduction

The notion of a quasi-Einstein manifold was studied in [3, 4] by M. C. Chaki and R. K. Maity. In [1] A. Bhattacharyya and T. De studied the notion of a mixed generalized quasi-Einstein manifold. A. Bhattacharyya, M. Tarafdar and D. Debnath [2] have obtained results on mixed super quasi-Einstein manifolds, they proved that a super quasi-umbilical hypersurface of Euclidean space is a mixed super quasi-Einstein manifold. S. Sular and C. Özgür [6] have proved that a quasi-umbilical hypersurface of Kenmotsu space forms is a generalized quasi-Einstein hypersurface. In this paper we study quasi-umbilical, generalized quasi-umbilical, super quasi-umbilical hypersurfaces of a complex space form. It is proved that these hypersurfaces are quasi-Einstein, mixed generalized quasi-Einstein and mixed super quasi-Einstein manifolds. respectively.

Definition 1.1 ([7]). A Kähler manifold is an even-dimensional manifold M^{2n} with a complex structure J and a positive definite metric g which satisfy the conditions

$$J^2 = -I, \quad g(JX, JY) = g(X, Y), \quad \nabla J = 0,$$

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where ∇ means the covariant derivation according to the Levi-Civita connection.

2. Preliminaries

Definition 2.1. A complex manifold with constant sectional curvature c is known as a complex space form. The curvature tensor of a complex space form is given by

$$\begin{aligned} \bar{R}(X, Y)Z = \frac{c}{4} [g(Y, Z)X - g(X, Z)Y + g(Z, JY)JX \\ - g(Z, JX)JY + g(X, JY)JZ]. \end{aligned} \quad (2.1)$$

Definition 2.2 ([5]). An almost Hermitian manifold M is called a generalized complex space form $M(f_1, f_2)$ if its Riemannian curvature tensor R satisfies

$$\begin{aligned} R(X, Y)Z = f_1 \{g(Y, Z)X - g(X, Z)Y\} + f_2 \{g(X, JZ)JY \\ - g(Y, JZ)JX + 2g(X, JY)JZ\} \end{aligned} \quad (2.2)$$

for all $X, Y, Z \in TM$, where f_1 and f_2 are smooth functions on M .

Definition 2.3. A non-flat Kähler manifold M^{2n} ($n \geq 2$) is said to be

- (i) a quasi-Einstein manifold if its Ricci tensor S is non zero and satisfies the condition

$$S(X, Y) = ag(X, Y) + bA(X)A(Y),$$

- (ii) a generalized quasi-Einstein manifold if

$$S(X, Y) = ag(X, Y) + bA(X)A(Y) + cB(X)B(Y),$$

- (iii) a mixed generalized quasi-Einstein manifold if

$$\begin{aligned} S(X, Y) = ag(X, Y) + bA(X)A(Y) + cB(X)B(Y) \\ + d[A(X)B(Y) + B(X)A(Y)], \end{aligned}$$

- (iv) a mixed super quasi-Einstein manifold if

$$\begin{aligned} S(X, Y) = ag(X, Y) + bA(X)A(Y) + cB(X)B(Y) \\ + d[A(X)B(Y) + B(X)A(Y)] + eD(X, Y), \end{aligned}$$

where a, b, c, d, e are non zero scalars, A and B are two non zero 1-forms such that

$$g(X, U) = A(X) \text{ and } g(X, V) = B(X) \quad \forall X \in TM,$$

U and V are unit vectors which are orthogonal, i.e.,

$$g(U, V) = 0.$$

D is a symmetric (0,2) tensor of zero trace which satisfies the condition

$$D(X, U) = 0, \quad \forall X \in TM.$$

3. Hypersurfaces of the complex space form

Let M be a hypersurface of a Kähler manifold M^{2n} .

If TM^{2n} and TM denote the Lie algebra of vector fields on M^{2n} and M , respectively, and $T^\perp M$ is the set of all vector fields normal to M , then Gauss and Weingarten formulae are, respectively, given by

$$\begin{aligned}\bar{\nabla}_X Y &= \nabla_X Y + \sigma(X, Y), \\ \bar{\nabla}_X N &= -A_N X + \nabla_X^\perp N,\end{aligned}$$

for all $X, Y \in TM$ and $N \in T^\perp M$, where ∇^\perp denotes the connection on the normal bundle $T^\perp M$. σ and A_N are the second fundamental forms and shape operator of immersion of M into M^{2n} corresponding to a normal vector field N and they are related as

$$g(A_N X, Y) = g(\sigma(X, Y), N).$$

The Gauss equation is given by

$$\begin{aligned}R(X, Y, Z, W) &= R(X, Y, Z, W) - g(\sigma(X, W), \sigma(Y, Z)) \\ &\quad + g(\sigma(Y, W), \sigma(X, Z)),\end{aligned}\tag{3.1}$$

where Z, W are vector fields tangents to M .

We need the following definitions.

Definition 3.1 ([2]). A hypersurface of a Kähler manifold M^{2n} is said to be

- (i) quasi-umbilical if its second fundamental tensor has the form

$$H(X, Y) = \alpha g(X, Y) + \beta \omega(X)\omega(Y),\tag{3.2}$$

- (ii) generalised quasi-umbilical if its second fundamental tensor has the form

$$H(X, Y) = \alpha g(X, Y) + \beta \omega(X)\omega(Y) + \gamma \delta(X)\delta(Y),\tag{3.3}$$

- (iii) super quasi-umbilical if its second fundamental tensor has the form

$$H(X, Y) = \alpha g(X, Y) + \beta \omega(X)\omega(Y) + \gamma \delta(X)\delta(Y) + \rho D(X, Y),\tag{3.4}$$

where $\alpha, \beta, \gamma, \rho$ are scalars and the vector fields corresponding to 1-forms ω and δ are unit vector fields.

Theorem 3.1. *Let $M^{2n}(c)$ be a complex space form.*

(i) *A quasi-umbilical hypersurface M of $M^{2n}(c)$ is a quasi-Einstein hypersurface.*

(ii) *A generalized quasi-umbilical hypersurface M of a $M^{2n}(c)$ is a mixed generalized quasi-Einstein manifold.*

(iii) *A super quasi-umbilical hypersurface M of $M^{2n}(c)$ is a mixed super quasi-Einstein manifold.*

Proof. (i) From equation (2.1), we have

$$\begin{aligned}\bar{R}(X, Y, Z, W) = & \frac{c}{4}[g(Y, Z)g(X, W) - g(X, Z)g(Y, W) \\ & + g(Z, JY)g(JX, W) - g(Z, JX)g(JY, W) \\ & + g(X, JY)g(JZ, W)]\end{aligned}\quad (3.5)$$

for all tangents X, Y, Z, W to M .

Let N be the unit normal vector field of M in $M^{2n}(c)$. Using $\sigma(X, Z) = H(X, Z)N$ in equation (3.1), we have

$$\begin{aligned}\bar{R}(X, Y, Z, W) = & R(X, Y, Z, W) - H(X, W)H(Y, Z) \\ & + H(Y, W)H(X, Z).\end{aligned}\quad (3.6)$$

For a quasi-umbilical hypersurface we know that

$$H(X, Z) = ag(X, Z) + b\omega(X)\omega(Z).\quad (3.7)$$

Putting (3.7) in (3.6) and using (3.5), we have

$$\begin{aligned}& \frac{c}{4}[g(Y, Z)g(X, W) - g(X, Z)g(Y, W) + g(Z, JY)g(JX, W) \\ & - g(Z, JX)g(JY, W) + g(X, JY)g(JZ, W)] \\ & = R(X, Y, Z, W) + a^2[g(X, Z)g(Y, W) - g(Y, Z)g(X, W)] \\ & + ab[g(X, Z)\omega(Y)\omega(W) + g(Y, W)\omega(X)\omega(Z) \\ & - g(Y, Z)\omega(X)\omega(W) - g(X, W)\omega(Y)\omega(Z)].\end{aligned}\quad (3.8)$$

Putting $X = W = e_i$ and taking the sum over i , ($1 \leq i \leq 2n$) in equation (3.8), where $\{e_i\}$ is an orthonormal basis for the given space form, we get

$$S(Y, Z) = \left[\frac{c}{4}(2n+1) + a^2(2n-1) + ab(2n-2)\right]g(Y, Z) + [2nab]\omega(Y)\omega(Z).$$

Hence M is a quasi-Einstein hypersurface.

Similar proofs of statements (ii) and (iii) are obtained by using equations (3.3), (3.4) and (3.5) in equation (3.6) and putting $X = W = e_i$. \square

4. Generalized complex space form with Bochner curvature tensor

Taking $X = e_i$ ($1 \leq i \leq 2n$), $Y = X$ and $Z = Y$ in the equation (2.2), we obtain for the curvature

$$\begin{aligned}R(e_i, X)Y = & F_1\{g(X, Y)e_i - g(e_i, Y)X\} + F_2\{g(e_i, JY)JX \\ & - g(X, JY)Je_i + 2g(e_i, JX)JY\}.\end{aligned}\quad (4.1)$$

Hence the Ricci tensor can be written in the form

$$S(X, Y) = \sum_{i=1}^{2n} R(e_i, X, Y, e_i) = \sum_{i=1}^{2n} g(R(e_i, X)Y, e_i),$$

and making use of (4.1) we can express it as

$$\begin{aligned} S(X, Y) &= F_1\{g(X, Y)2n - g(X, Y)\} + F_2\{g(X, Y) + 2g(X, Y)\} \\ &= \{(2n - 1)F_1 + 3F_2\}g(X, Y). \end{aligned} \quad (4.2)$$

For a generalized complex space form the Bochner curvature tensor is given by

$$\begin{aligned} B(X, Y)Z &= R(X, Y)Z + \frac{1}{2n+4} [g(X, Z)QY - S(Y, Z)X - g(Y, Z)QX \\ &\quad + S(X, Z)Y + g(JX, Z)QJY - S(JY, Z)JX - g(JY, Z)QJX \\ &\quad + S(JX, Z)JY + 2S(JX, Y)JZ + 2g(JX, Y)QJZ] \\ &\quad - \frac{D+2n}{2n+4} [g(JX, Z)JY - g(JY, Z)JX + 2g(JX, Y)JZ] \\ &\quad - \frac{D-4}{2n+4} [g(X, Z)Y - g(Y, Z)X] \end{aligned}$$

with $D = \frac{r+2n}{2n+2}$. R, S, Q and r are the Riemannian curvature tensor, the Ricci tensor, the Ricci operator and the scalar curvature of the manifold, respectively.

Suppose $B(X, Y)Z = 0$. Then the curvature (1,3)-tensor is

$$\begin{aligned} R(X, Y)Z &= \frac{-1}{2n+4} [g(X, Z)QY - S(Y, Z)X - g(Y, Z)QX \\ &\quad + S(X, Z)Y + g(JX, Z)QJY - S(JY, Z)JX - g(JY, Z)QJX \\ &\quad + S(JX, Z)JY + 2S(JX, Y)JZ + 2g(JX, Y)QJZ] \\ &\quad + \frac{D+2n}{2n+4} [g(JX, Z)JY - g(JY, Z)JX + 2g(JX, Y)JZ] \\ &\quad + \frac{D-4}{2n+4} [g(X, Z)Y - g(Y, Z)X]. \end{aligned}$$

It follows from the previous formula that the curvature (0,4)-tensor can be written as

$$\begin{aligned} R(X, Y, Z, W) &= g(R(X, Y)Z, W) \\ &= -1/(2n+4) [g(X, Z)g(QY, W) - S(Y, Z)g(X, W) \\ &\quad - g(Y, Z)g(QX, W) + S(X, Z)g(Y, W) \\ &\quad + g(JX, Z)g(QJY, W) - S(JY, Z)g(JX, W) \\ &\quad - g(JY, Z)g(QJX, W) + S(JX, Z)g(JY, W) \\ &\quad + 2S(JX, Y)g(JZ, W) + 2g(JX, Y)g(QJZ, W)] \\ &\quad + \frac{(\frac{r+2n}{2n+2}) + 2n}{2n+4} [g(JX, Z)g(JY, W) \\ &\quad - g(JY, Z)g(JX, W) + 2g(JX, Y)g(JZ, W)] \end{aligned}$$

$$+ \frac{\left(\frac{r+2n}{2n+2}\right) - 4}{2n+4} [g(X, Z)g(Y, W) - g(Y, Z)g(X, W)].$$

Putting $X = W = e_i$, where $\{e_i\}$, $i = 1, 2, \dots, 2n$, is a local orthonormal basis for vector fields in a generalized complex space form $N(F_1, F_2)$, by virtue of $S(X, Y) = \sum_{i=1}^{2n} g(R(e_i, X)Y, e_i)$, we get

$$S(Y, Z) = \{(2n - 1)F_1 + 3F_2 - 2\}g(Y, Z). \quad (4.3)$$

Hence $N(F_1, F_2)$ is the Einstein manifold.

From (4.3), we have

$$QY = \{(2n - 1)F_1 + 3F_2 - 2\}Y \quad (4.4)$$

and

$$r = 2n\{(2n - 1)F_1 + 3F_2 - 2\}. \quad (4.5)$$

Thus we can state the following theorem.

Theorem 4.1. *A Bochner flat space of generalized complex space form $N(F_1, F_2)$ is an Einstein manifold. The Ricci tensor S , Ricci operator Q and scalar curvature r are given in equations (4.3)–(4.5).*

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