

On concircular curvature tensor in a Lorentzian α -Sasakian manifold with respect to the quarter-symmetric non-metric connection

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ABSTRACT. In the present paper, some properties of concircular curvature tensor in a Lorentzian α -Sasakian manifold with respect to the quarter-symmetric non-metric connection have been studied.

1. Introduction

In a Riemannian manifold M , a linear connection $\bar{\nabla}$ is called a quarter-symmetric connection [6] if the torsion tensor T of the connection $\bar{\nabla}$,

$$T(X, Y) = \bar{\nabla}_X Y - \bar{\nabla}_Y X - [X, Y],$$

satisfies

$$T(X, Y) = \eta(Y)\phi X - \eta(X)\phi Y,$$

where η is a 1-form and ϕ is a $(1, 1)$ tensor field. If, moreover, a quarter-symmetric connection $\bar{\nabla}$ satisfies the condition

$$(\bar{\nabla}_X g)(Y, Z) = -\eta(Y)g(\phi X, Z) - \eta(Z)g(Y, \phi X),$$

where $X, Y, Z \in \chi(M)$ and $\chi(M)$ is the set of all differentiable vector fields on M , then $\bar{\nabla}$ is said to be a quarter-symmetric non-metric connection. If we change ϕX by X , then the connection reduces to a semi-symmetric non-metric connection [12]. Thus the notion of quarter-symmetric connection generalizes the notion of semi-symmetric connection.

A relation between the quarter-symmetric non-metric connection $\bar{\nabla}$ and the Levi-Civita connection ∇ in an n -dimensional Lorentzian α -Sasakian

Received November 6, 2017.

2010 *Mathematics Subject Classification.* 53D15; 53C05; 53C25.

Key words and phrases. Lorentzian α -Sasakian manifold; concircular curvature tensor; quarter-symmetric non-metric connection.

<http://dx.doi.org/10.12697/ACUTM.2018.22.23>

manifold M is given by

$$\bar{\nabla}_X Y = \nabla_X Y + \eta(Y)\phi X. \quad (1.1)$$

A transformation of an n -dimensional Riemannian manifold M , which transforms every geodesic circle of M into a geodesic circle, is called a concircular transformation [8, 11]. A concircular transformation is always a conformal transformation [8]. Here geodesic circle means a curve in M whose first curvature is constant and second curvature is identically zero. Thus the geometry of concircular transformations, i.e., the concircular geometry, is a generalization of inversive geometry in the sense that the change of metric is more general than induced by a circle preserving diffeomorphism. An interesting invariant of a concircular transformation is the concircular curvature tensor with respect to the Levi-Civita connection. It is defined by (see [11])

$$C(X, Y)Z = R(X, Y)Z - \frac{r}{n(n-1)}[g(Y, Z)X - g(X, Z)Y], \quad (1.2)$$

where $X, Y, Z \in \chi(M)$, R and r are, respectively, the curvature tensor and the scalar curvature with respect to the Levi-Civita connection. A Riemannian manifold with vanishing concircular curvature tensor is of constant curvature. Thus, the concircular curvature tensor is the measure of the failure of a Riemannian manifold to be of constant curvature. Recently, concircular curvature tensor have been studied by various authors such as Acet and Perktas [1], Barman and Ghosh [3], Haseeb [7], Taleshian and Asghari [10], and many others.

In 2005, Yildiz and Murathan [13] studied Lorentzian α -Sasakian manifolds with conformally flat and quasi-conformally flat conditions. In 2009, Yildiz et al. [15], further studied Lorentzian α -Sasakian manifolds and proved that ϕ -conformally flat, ϕ -conharmonically flat, ϕ -projectively flat and ϕ -concentrically flat Lorentzian α -Sasakian manifolds are η -Einstein manifolds. Recently, De and Majhi [5] studied ϕ -Weyl semisymmetric and ϕ -projectively semisymmetric generalized Sasakian space-forms.

The paper is organized as follows. In Section 2 we give a brief introduction of Lorentzian α -Sasakian manifolds. In Section 3 we deduce the relation between the curvature tensors of Lorentzian α -Sasakian manifolds with respect to the quarter-symmetric non-metric connection and the Levi-Civita connection. Sections 4, 5, 6, and 7 are devoted to study ξ -concentrically flat, quasi-concentrically flat, pseudoconcentrically flat, and ϕ -concentrically flat Lorentzian α -Sasakian manifolds with respect to the quarter-symmetric non-metric connection, respectively. In the last Section 8 we study ϕ -semisymmetric Lorentzian α -Sasakian manifolds with respect to the quarter-symmetric non-metric connection.

2. Preliminaries

A differentiable manifold M of dimension n is called a Lorentzian α -Sasakian manifold, if it admits a $(1, 1)$ tensor field ϕ , a contravariant vector field ξ , a covariant vector field η , and a Lorentzian metric g which satisfy the conditions (see [4])

$$\begin{aligned} \phi^2 X &= X + \eta(X)\xi, \\ \eta(\xi) &= -1, \quad \phi\xi = 0, \quad \eta(\phi X) = 0, \quad g(X, \xi) = \eta(X), \\ g(\phi X, \phi Y) &= g(X, Y) + \eta(X)\eta(Y), \quad g(\phi X, Y) = g(X, \phi Y) \end{aligned} \tag{2.1}$$

for all vector fields X, Y on M .

Also Lorentzian α -Sasakian manifolds satisfy the equations (see [13]–[15])

$$\begin{aligned} \nabla_X \xi &= -\alpha\phi X, \\ \Phi(X, Y) &= (\nabla_X \eta)Y = -\alpha g(\phi X, Y), \end{aligned} \tag{2.3}$$

where ∇ denotes the operator of covariant differentiation with respect to the Lorentzian metric g , and $\alpha \in R$.

Further, on a Lorentzian α -Sasakian manifold M , the following relations hold (see [2, 13, 15]):

$$\begin{aligned} g(R(X, Y)Z, \xi) &= \eta(R(X, Y)Z) = \alpha^2[g(Y, Z)\eta(X) - g(X, Z)\eta(Y)], \\ R(\xi, X)Y &= \alpha^2[g(X, Y)\xi - \eta(Y)X], \\ R(X, Y)\xi &= \alpha^2[\eta(Y)X - \eta(X)Y], \\ R(\xi, X)\xi &= \alpha^2[X + \eta(X)\xi], \\ S(X, \xi) &= (n - 1)\alpha^2\eta(X), \quad S(\xi, \xi) = -(n - 1)\alpha^2, \\ Q\xi &= (n - 1)\alpha^2\xi, \\ (\nabla_X \phi)Y &= \alpha[g(X, Y)\xi - \eta(Y)X], \end{aligned} \tag{2.4}$$

$$S(\phi Y, \phi Z) = S(Y, Z) + (n - 1)\alpha^2 g(Y, Z) \tag{2.5}$$

for any vector fields X, Y and Z on M .

Example 2.1. We consider the 3-dimensional manifold $M^3 = \{(x, y, z) \in \mathbb{R}^3 : z > 0\}$, where (x, y, z) are standard coordinates of \mathbb{R}^3 . Let e_1, e_2 and e_3 be the vector fields on M^3 given by

$$e_1 = z \frac{\partial}{\partial x}, \quad e_2 = z \frac{\partial}{\partial y}, \quad e_3 = z \frac{\partial}{\partial z} = \xi,$$

which are linearly independent at each point of M^3 , and hence form a basis of $T_p M^3$. Define a Lorentzian metric g on M^3 as

$$\begin{aligned} g(e_1, e_1) &= 1, \quad g(e_2, e_2) = 1, \quad g(e_3, e_3) = -1, \\ g(e_1, e_2) &= g(e_1, e_3) = g(e_2, e_3) = 0. \end{aligned}$$

Let η be the 1-form on M^3 defined as $\eta(X) = g(X, e_3) = g(X, \xi)$ for all $X \in \chi(M)$, and let ϕ be the $(1, 1)$ tensor field on M^3 defined as

$$\phi e_1 = -e_1, \phi e_2 = -e_2, \phi e_3 = 0.$$

By applying linearity of ϕ and g , we have

$$\begin{aligned} \eta(\xi) &= g(\xi, \xi) = -1, \phi^2 X = X + \eta(X)\xi, \eta(\phi X) = 0, \\ g(X, \xi) &= \eta(X), g(\phi X, \phi Y) = g(X, Y) + \eta(X)\eta(Y) \end{aligned}$$

for all $X, Y \in \chi(M)$.

Let ∇ be the Levi-Civita connection with respect to the Lorentzian metric g . Then we have

$$\begin{aligned} [e_1, e_2] &= 0, [e_2, e_1] = 0, [e_1, e_3] = -e_1, \\ [e_3, e_1] &= e_1, [e_2, e_3] = -e_2, [e_3, e_2] = e_2. \end{aligned}$$

The Riemannian connection ∇ of the Lorentzian metric g is given by

$$\begin{aligned} 2g(\nabla_X Y, Z) &= Xg(Y, Z) + Yg(Z, X) - Zg(X, Y) - g(X, [Y, Z]) \\ &\quad + g(Y, [Z, X]) + g(Z, [X, Y]), \end{aligned}$$

which is known as Koszul's formula (see [4]). Using Koszul's formula, we can easily calculate

$$\begin{aligned} \nabla_{e_1} e_1 &= -e_3, \nabla_{e_1} e_2 = 0, \nabla_{e_1} e_3 = -e_1, \nabla_{e_2} e_1 = 0, \nabla_{e_2} e_2 = -e_3, \\ \nabla_{e_2} e_3 &= -e_2, \nabla_{e_3} e_1 = 0, \nabla_{e_3} e_2 = 0, \nabla_{e_3} e_3 = 0. \end{aligned} \quad (2.6)$$

Now let

$$\begin{aligned} X &= \sum_{i=1}^3 X^i e_i = X^1 e_1 + X^2 e_2 + X^3 e_3, \\ Y &= \sum_{j=1}^3 Y^j e_j = Y^1 e_1 + Y^2 e_2 + Y^3 e_3, \\ Z &= \sum_{k=1}^3 Z^k e_k = Z^1 e_1 + Z^2 e_2 + Z^3 e_3 \end{aligned}$$

for all $X, Y, Z \in \chi(M)$. It is known that

$$R(X, Y)Z = \nabla_X \nabla_Y Z - \nabla_Y \nabla_X Z - \nabla_{[X, Y]} Z. \quad (2.7)$$

From the equations (2.6) and (2.7), it can be easily verified that

$$\begin{aligned} R(e_1, e_2)e_1 &= -e_2, R(e_1, e_3)e_1 = -e_3, R(e_2, e_3)e_1 = 0, \\ R(e_1, e_2)e_2 &= e_1, R(e_1, e_3)e_2 = 0, R(e_2, e_3)e_2 = -e_3, \\ R(e_1, e_2)e_3 &= 0, R(e_1, e_3)e_3 = -e_1, R(e_2, e_3)e_3 = -e_2. \end{aligned} \quad (2.8)$$

From (2.8), it follows that

$$R(X, Y)Z = g(Y, Z)X - g(X, Z)Y.$$

Thus, for $e_3 = \xi$, the manifold M^3 is a Lorentzian almost contact metric manifold of constant curvature 1 and is locally isometric to the unit sphere $S^3(1)$.

Definition 2.2 (see [15]). A Lorentzian α -Sasakian manifold M is said to be an η -Einstein manifold if its Ricci tensor S is of the form

$$S(X, Y) = ag(X, Y) + b\eta(X)\eta(Y),$$

where a and b are scalar functions on M .

A Lorentzian α -Sasakian manifold M is said to be a generalized η -Einstein manifold if its Ricci tensor S is of the form

$$S(X, Y) = ag(X, Y) + b\eta(X)\eta(Y) + c\Omega(X, Y),$$

where a, b, c are scalar functions on M and $\Omega(X, Y) = g(\phi X, Y)$. If $c = 0$, then it reduces to an η -Einstein manifold.

3. Curvature tensor of Lorentzian α -Sasakian manifolds with respect to the quarter-symmetric non-metric connection

The curvature tensor \bar{R} of a Lorentzian α -Sasakian manifold with respect to the quarter-symmetric non-metric connection $\bar{\nabla}$ is defined by

$$\bar{R}(X, Y)Z = \bar{\nabla}_X \bar{\nabla}_Y Z - \bar{\nabla}_Y \bar{\nabla}_X Z - \bar{\nabla}_{[X, Y]} Z. \tag{3.1}$$

From the equations (1.1), (2.1), (2.3), (2.4), and (3.1), we get

$$\begin{aligned} \bar{R}(X, Y)Z &= R(X, Y)Z + \alpha[g(\phi Y, Z)\phi X - g(\phi X, Z)\phi Y] \\ &\quad + \alpha[\eta(X)Y - \eta(Y)X]\eta(Z), \end{aligned} \tag{3.2}$$

where

$$R(X, Y)Z = \nabla_X \nabla_Y Z - \nabla_Y \nabla_X Z - \nabla_{[X, Y]} Z$$

is the Riemannian curvature tensor of the connection ∇ . Contracting X in (3.2), we get

$$\bar{S}(Y, Z) = S(Y, Z) + \alpha g(\phi Y, Z)\psi - \alpha g(Y, Z) - \alpha n\eta(Y)\eta(Z), \tag{3.3}$$

where S and \bar{S} are the Ricci tensors with respect to the connections ∇ and $\bar{\nabla}$, respectively, on M and $\psi = \text{trace } \phi$. Contracting again Y and Z in (3.3), we get

$$\bar{r} = r + \alpha\psi^2, \tag{3.4}$$

where r and \bar{r} are, respectively, the scalar curvatures with respect to the connections ∇ and $\bar{\nabla}$ on M .

Lemma 3.1. *Let M be an n -dimensional Lorentzian α -Sasakian manifold with respect to the quarter-symmetric non-metric connection. Then we have*

$$\bar{R}(X, Y)\xi = (\alpha^2 + \alpha)[\eta(Y)X - \eta(X)Y], \tag{3.5}$$

$$\begin{aligned}
\bar{R}(\xi, X)Y &= -\bar{R}(X, \xi)Y \\
&= \alpha^2 g(X, Y)\xi - (\alpha^2 + \alpha)\eta(Y)X - \alpha\eta(X)\eta(Y)\xi, \\
\bar{R}(\xi, X)\xi &= (\alpha^2 + \alpha)[X + \eta(X)\xi], \\
\bar{S}(X, \xi) &= (n-1)(\alpha^2 + \alpha)\eta(X), \quad \bar{S}(\xi, \xi) = -(n-1)(\alpha^2 + \alpha), \\
\bar{Q}\xi &= (n-1)(\alpha^2 + \alpha)\xi
\end{aligned} \tag{3.6}$$

for all $X, Y \in \chi(M)$.

4. ξ -Concircularly flat Lorentzian α -Sasakian manifolds with respect to the quarter-symmetric non-metric connection

Analogous to the equation (1.2), the concircular curvature tensor \bar{C} with respect to the quarter-symmetric non-metric connection is given by

$$\bar{C}(X, Y)Z = \bar{R}(X, Y)Z - \frac{\bar{r}}{n(n-1)}[g(Y, Z)X - g(X, Z)Y], \tag{4.1}$$

where \bar{R} and \bar{r} are, respectively, the Riemannian curvature tensor and the scalar curvature with respect to the connection $\bar{\nabla}$.

Definition 4.1. A Lorentzian α -Sasakian manifold with respect to the quarter-symmetric non-metric connection is said to be ξ -concircularly flat if

$$\bar{C}(X, Y)\xi = 0 \tag{4.2}$$

for all X, Y on M .

Taking $Z = \xi$ in (4.1) and then using (2.1), (3.4), and (3.5), we have

$$\bar{C}(X, Y)\xi = \left[(\alpha^2 + \alpha) - \frac{r + \alpha\psi^2}{n(n-1)} \right] [\eta(Y)X - \eta(X)Y]. \tag{4.3}$$

From the equations (4.2) and (4.3), it follows that

$$\left[(\alpha^2 + \alpha) - \frac{r + \alpha\psi^2}{n(n-1)} \right] [\eta(Y)X - \eta(X)Y] = 0. \tag{4.4}$$

Taking $Y = \xi$ in (4.4) and using (2.1), we have

$$\left[(\alpha^2 + \alpha) - \frac{r + \alpha\psi^2}{n(n-1)} \right] [X + \eta(X)\xi] = 0. \tag{4.5}$$

Now taking inner product of (4.5) with U , we find

$$\left[(\alpha^2 + \alpha) - \frac{r + \alpha\psi^2}{n(n-1)} \right] [g(X, U) + \eta(X)\eta(U)] = 0. \tag{4.6}$$

By replacing X by QX in (4.6) and using the fact that $S(X, U) = g(QX, U)$, we obtain

$$\left[(\alpha^2 + \alpha) - \frac{r + \alpha\psi^2}{n(n-1)} \right] [S(X, U) + \alpha^2(n-1)\eta(X)\eta(U)] = 0.$$

This implies that either the scalar curvature of M is $n(n - 1)(\alpha^2 + \alpha) - \alpha\psi^2$ or

$$S(X, U) = -\alpha^2(n - 1)\eta(X)\eta(U).$$

Hence, we can state the following theorem.

Theorem 4.2. *For a ξ -concircularly flat Lorentzian α -Sasakian manifold with respect to the quarter-symmetric non-metric connection, either the scalar curvature is $n(n - 1)(\alpha^2 + \alpha) - \alpha\psi^2$ or the manifold is a special type of η -Einstein manifold with respect to the Levi-Civita connection.*

5. Quasi-concircularly flat Lorentzian α -Sasakian manifolds with respect to the quarter-symmetric non-metric connection

Definition 5.1. A Lorentzian α -Sasakian manifold with respect to the quarter-symmetric non-metric connection is said to be quasi-concircularly flat if

$$g[\bar{C}(X, Y)Z, \phi W] = 0 \tag{5.1}$$

for all X, Y, Z, W on M .

Let M be an n -dimensional quasi-concircularly flat Lorentzian α -Sasakian manifold with respect to the quarter-symmetric non-metric connection. Therefore, from (4.1) and (5.1), it follows that

$$g[\bar{R}(X, Y)Z, \phi W] = \frac{\bar{r}}{n(n - 1)}[g(Y, Z)g(X, \phi W) - g(X, Z)g(Y, \phi W)],$$

which by using (3.2) takes the form

$$\begin{aligned} g[R(X, Y)Z, \phi W] &= -\alpha[g(\phi Y, Z)g(\phi X, \phi W) \\ &\quad - g(\phi X, Z)g(\phi Y, \phi W)] \\ &\quad - \alpha[\eta(X)g(Y, \phi W) - \eta(Y)g(X, \phi W)]\eta(Z) \\ &\quad + \frac{\bar{r}}{n(n - 1)}[g(Y, Z)g(X, \phi W) - g(X, Z)g(Y, \phi W)]. \end{aligned} \tag{5.2}$$

Let $\{e_1, e_2, \dots, e_{n-1}, \xi\}$ be a local orthonormal basis of vector fields in M . Then $\{\phi e_1, \phi e_2, \dots, \phi e_{n-1}, \xi\}$ is also a local orthonormal basis. If we put

$X = \phi e_i$ and $W = e_i$ in (5.2) and sum up with respect to i , then we have

$$\begin{aligned} \sum_{i=1}^{n-1} g[R(\phi e_i, Y)Z, \phi e_i] &= -\alpha \sum_{i=1}^{n-1} [g(\phi Y, Z)g(\phi^2 e_i, \phi e_i) \\ &\quad - g(\phi^2 e_i, Z)g(\phi Y, \phi e_i)] \\ &\quad - \alpha \sum_{i=1}^{n-1} [\eta(\phi e_i)g(Y, \phi e_i) - \eta(Y)g(\phi e_i, \phi e_i)]\eta(Z) \\ &\quad + \frac{\bar{r}}{n(n-1)} \sum_{i=1}^{n-1} [g(Y, Z)g(\phi e_i, \phi e_i) - g(\phi e_i, Z)g(Y, \phi e_i)]. \end{aligned} \quad (5.3)$$

It can be easily verified that

$$\begin{aligned} \sum_{i=1}^{n-1} g[R(\phi e_i, Y)Z, \phi e_i] &= S(Y, Z) - \alpha^2 [g(Y, Z) + \eta(Y)\eta(Z)], \\ \sum_{i=1}^{n-1} g(\phi^2 e_i, \phi e_i) &= \psi, \quad \sum_{i=1}^{n-1} g(\phi e_i, \phi e_i) = (n-1), \end{aligned} \quad (5.4)$$

$$\sum_{i=1}^{n-1} \eta(\phi e_i)g(Y, \phi e_i) = 0,$$

$$\sum_{i=1}^{n-1} g(\phi^2 e_i, Z)g(\phi Y, \phi e_i) = g(Y, Z) + \eta(Y)\eta(Z),$$

$$\sum_{i=1}^{n-1} g(\phi e_i, Z)g(Y, \phi e_i) = g(Y, Z) + \eta(Y)\eta(Z).$$

Thus, by virtue of (3.4), the equation (5.3) takes the form

$$\begin{aligned} S(Y, Z) &= \left[\alpha^2 + \alpha + \frac{(r + \alpha\psi^2)(n-2)}{n(n-1)} \right] g(Y, Z) \\ &\quad + \left[\alpha^2 + n\alpha - \frac{r + \alpha\psi^2}{n(n-1)} \right] \eta(Y)\eta(Z) - \alpha\psi g(\phi Y, Z), \end{aligned}$$

where $\psi = \text{trace } \phi$. Thus we can state the following theorem.

Theorem 5.2. *A quasi-concircularly flat Lorentzian α -Sasakian manifold with respect to the quarter-symmetric non-metric connection is a generalized η -Einstein manifold with respect to the Levi-Civita connection.*

6. Pseudoconircularly flat Lorentzian α -Sasakian manifolds with respect to the quarter-symmetric non-metric connection

Definition 6.1. A Lorentzian α -Sasakian manifold with respect to the quarter-symmetric non-metric connection is said to be pseudoconircularly flat if

$$g[\bar{C}(\phi X, Y)Z, \phi W] = 0 \tag{6.1}$$

for all X, Y, Z, W on M .

Let M be an n -dimensional pseudoconircularly flat Lorentzian α -Sasakian manifold with respect to the quarter-symmetric non-metric connection. Therefore, from (4.1) and (6.1), it follows that

$$g[\bar{R}(\phi X, Y)Z, \phi W] = \frac{\bar{r}}{n(n-1)}[g(Y, Z)g(\phi X, \phi W) - g(\phi X, Z)g(Y, \phi W)],$$

which in view of (3.2) takes the form

$$\begin{aligned} g[R(\phi X, Y)Z, \phi W] &= \alpha[g(X, Z)g(\phi Y, \phi W) + \eta(X)\eta(Z)g(\phi Y, \phi W) \\ &\quad - g(\phi Y, Z)g(X, \phi W) + \eta(Y)\eta(Z)g(\phi X, \phi W)] \\ &\quad + \frac{\bar{r}}{n(n-1)}[g(Y, Z)g(\phi X, \phi W) - g(\phi X, Z)g(Y, \phi W)]. \end{aligned} \tag{6.2}$$

In view of (2.2), (6.2) becomes

$$\begin{aligned} g[R(\phi X, Y)Z, \phi W] &= \alpha[g(X, Z)g(Y, W) + g(X, Z)\eta(Y)\eta(W) \\ &\quad + g(Y, W)\eta(X)\eta(Z) + 2\eta(X)\eta(Z)\eta(Y)\eta(W) \\ &\quad - g(\phi Y, Z)g(X, \phi W) + g(X, W)\eta(Y)\eta(Z)] \\ &\quad + \frac{\bar{r}}{n(n-1)}[g(Y, Z)g(X, W) + g(Y, Z)\eta(X)\eta(W) \\ &\quad - g(\phi X, Z)g(Y, \phi W)]. \end{aligned} \tag{6.3}$$

Let $\{e_1, e_2, \dots, e_{n-1}, \xi\}$ be a local orthonormal basis of vector fields in M . Then $\{\phi e_1, \phi e_2, \dots, \phi e_{n-1}, \xi\}$ is also a local orthonormal basis. If we put $X = W = e_i$ in (6.3) and sum up with respect to i , then we have

$$\begin{aligned} \sum_{i=1}^{n-1} g[R(\phi e_i, Y)Z, \phi e_i] &= \alpha \sum_{i=1}^{n-1} [g(e_i, Z)g(Y, e_i) + g(e_i, Z)\eta(Y)\eta(e_i) \\ &\quad + g(Y, e_i)\eta(e_i)\eta(Z) + 2\eta(e_i)\eta(e_i)\eta(Z)\eta(Y) - g(e_i, \phi e_i)g(\phi Y, Z) \\ &\quad + g(e_i, e_i)\eta(Y)\eta(Z)] + \frac{\bar{r}}{n(n-1)} \sum_{i=1}^{n-1} [g(Y, Z)g(e_i, e_i) \\ &\quad + g(Y, Z)\eta(e_i)\eta(e_i) - g(\phi e_i, Z)g(Y, \phi e_i)]. \end{aligned} \tag{6.4}$$

It can be easily verified that

$$\sum_{i=1}^{n-1} g[R(\phi e_i, Y)Z, \phi e_i] = S(Y, Z) - \alpha^2[g(Y, Z) + \eta(Y)\eta(Z)], \quad (6.5)$$

$$\sum_{i=1}^{n-1} g(e_i, Z)g(Y, e_i) = \sum_{i=1}^{n-1} g(\phi e_i, Z)g(Y, \phi e_i) = g(Y, Z) + \eta(Y)\eta(Z), \quad (6.6)$$

$$\sum_{i=1}^{n-1} g(e_i, e_i) = (n-1). \quad (6.7)$$

By virtue of (3.4) and (6.5)–(6.7), the equation (6.4) takes the form

$$\begin{aligned} S(Y, Z) &= [\alpha^2 + \alpha + \frac{(r + \alpha\psi^2)(n-2)}{n(n-1)}]g(Y, Z) \\ &+ [\alpha^2 + \alpha n - \frac{r + \alpha\psi^2}{n(n-1)}]\eta(Y)\eta(Z) - \alpha\psi g(\phi Y, Z), \end{aligned}$$

where $\psi = \text{trace } \phi$. Thus we can state the following theorem.

Theorem 6.2. *A pseudoconcentrically flat Lorentzian α -Sasakian manifold with respect to the quarter-symmetric non-metric connection is a generalized η -Einstein manifold with respect to the Levi-Civita connection.*

7. ϕ -Concentrically flat Lorentzian α -Sasakian manifolds with respect to the quarter-symmetric non-metric connection

Definition 7.1. A Lorentzian α -Sasakian manifold with respect to the quarter-symmetric non-metric connection is said to be ϕ -concentrically flat if (see [9])

$$\phi^2 \bar{C}(\phi X, \phi Y)\phi Z = 0 \quad (7.1)$$

for all X, Y, Z on M .

Let M be an n -dimensional ϕ -concentrically flat Lorentzian α -Sasakian manifold with respect to the quarter-symmetric non-metric connection. Then from (7.1) it follows that

$$g(\bar{C}(\phi X, \phi Y)\phi Z, \phi W) = 0. \quad (7.2)$$

In view of (4.1), (7.2) becomes

$$\begin{aligned} g[\bar{R}(\phi X, \phi Y)\phi Z, \phi W] &= \frac{\bar{r}}{n(n-1)} [g(\phi Y, \phi Z)g(\phi X, \phi W) \\ &- g(\phi X, \phi Z)g(\phi Y, \phi W)], \end{aligned}$$

which in view of (3.2) takes the form

$$g[R(\phi X, \phi Y)\phi Z, \phi W] = \alpha[g(X, \phi Z)g(Y, \phi W) - g(Y, \phi Z)g(X, \phi W)] + \frac{\bar{r}}{n(n-1)} [g(\phi Y, \phi Z)g(\phi X, \phi W) - g(\phi X, \phi Z)g(\phi Y, \phi W)]. \tag{7.3}$$

Let $\{e_1, e_2, \dots, e_{n-1}, \xi\}$ be a local orthonormal basis of vector fields in M . Then $\{\phi e_1, \phi e_2, \dots, \phi e_{n-1}, \xi\}$ is also a local orthonormal basis. If we put $X = W = e_i$ in (7.4) and sum up with respect to i , then we have

$$\sum_{i=1}^{n-1} g[R(\phi e_i, \phi Y)\phi Z, \phi e_i] = \alpha \sum_{i=1}^{n-1} [g(e_i, \phi Z)g(Y, \phi e_i) - g(Y, \phi Z)g(e_i, \phi e_i)] + \frac{\bar{r}}{n(n-1)} \sum_{i=1}^{n-1} [g(\phi Y, \phi Z)g(\phi e_i, \phi e_i) - g(\phi e_i, \phi Z)g(\phi Y, \phi e_i)]. \tag{7.4}$$

It can be easily verified that

$$\sum_{i=1}^{n-1} g[R(\phi e_i, \phi Y)\phi Z, \phi e_i] = S(\phi Y, \phi Z) - \alpha^2 g(\phi Y, \phi Z), \tag{7.5}$$

$$\sum_{i=1}^{n-1} g(\phi e_i, \phi Z)g(\phi Y, \phi e_i) = g(\phi Y, \phi Z). \tag{7.6}$$

By virtue of (5.4), (6.6), (7.5), and (7.6), the equation (7.4) gives

$$S(\phi Y, \phi Z) = \left[\frac{\bar{r}(n-2)}{n(n-1)} + \alpha^2 \right] g(\phi Y, \phi Z) + \alpha g(Y, Z) + \alpha \eta(Y)\eta(Z) - \alpha g(Y, \phi Z)\psi$$

which in view of (2.2), (2.5), and (3.4) turns to

$$S(Y, Z) = \left[\frac{(r + \alpha\psi^2)(n-2)}{n(n-1)} - (n-2)\alpha^2 + \alpha \right] g(Y, Z) + \left[\frac{(r + \alpha\psi^2)(n-2)}{n(n-1)} + \alpha^2 + \alpha \right] \eta(Y)\eta(Z) - \alpha g(Y, \phi Z)\psi,$$

where $\psi = \text{trace } \phi$. Thus we can state the following theorem.

Theorem 7.2. *A ϕ -conircularly flat Lorentzian α -Sasakian manifold with respect to the quarter-symmetric non-metric connection is a generalized η -Einstein manifold with respect to the Levi-Civita connection.*

8. ϕ -Concircularly semisymmetric Lorentzian α -Sasakian manifolds with respect to the quarter-symmetric non-metric connection

Definition 8.1. A Lorentzian α -Sasakian manifold with respect to the quarter-symmetric non-metric connection is said to be ϕ -concircularly semisymmetric if (see [5])

$$\bar{C}(X, Y) \cdot \phi = 0$$

for all X, Y on M .

Let M be an n -dimensional ϕ -concircularly semisymmetric Lorentzian α -Sasakian manifold with respect to the quarter-symmetric non-metric connection. Therefore $\bar{C}(X, Y) \cdot \phi = 0$ turns into

$$(\bar{C}(X, Y) \cdot \phi)Z = \bar{C}(X, Y)\phi Z - \phi\bar{C}(X, Y)Z = 0,$$

which, by $X = \xi$, takes the form

$$(\bar{C}(\xi, Y) \cdot \phi)Z = \bar{C}(\xi, Y)\phi Z - \phi\bar{C}(\xi, Y)Z = 0. \quad (8.1)$$

Taking $X = \xi$ in (4.1) and using (2.1), we have

$$\bar{C}(\xi, Y)Z = \bar{R}(\xi, Y)Z - \frac{\bar{r}}{n(n-1)}[g(Y, Z)\xi - \eta(Z)Y].$$

In view of (3.6), it becomes

$$\begin{aligned} \bar{C}(\xi, Y)Z &= \left[\alpha^2 - \frac{\bar{r}}{n(n-1)} \right] g(Y, Z)\xi \\ &\quad - \left[(\alpha^2 + \alpha) - \frac{\bar{r}}{n(n-1)} \right] \eta(Z)Y - \alpha\eta(Y)\eta(Z)\xi \end{aligned} \quad (8.2)$$

from which we get

$$\phi\bar{C}(\xi, Y)Z = -\left[(\alpha^2 + \alpha) - \frac{\bar{r}}{n(n-1)} \right] \eta(Z)\phi Y. \quad (8.3)$$

Replacing Z by ϕZ in (8.2) and using (2.1), we get

$$\bar{C}(\xi, Y)\phi Z = \left[\alpha^2 - \frac{\bar{r}}{n(n-1)} \right] g(Y, \phi Z)\xi. \quad (8.4)$$

Therefore, combining (8.1), (8.3), and (8.4), we have

$$\left[\alpha^2 - \frac{\bar{r}}{n(n-1)} \right] g(Y, \phi Z)\xi + \left[(\alpha^2 + \alpha) - \frac{\bar{r}}{n(n-1)} \right] \eta(Z)\phi Y = 0. \quad (8.5)$$

Taking inner product of (8.5) with ξ and using (2.1), we find

$$\left[\alpha^2 - \frac{\bar{r}}{n(n-1)} \right] g(Y, \phi Z) = 0.$$

Since $g(X, \phi Z) \neq 0$, we get

$$\bar{r} = n(n-1)\alpha^2 \quad \implies \quad r = n(n-1)\alpha^2 - \alpha\psi^2.$$

Thus we can state the following theorem.

Theorem 8.2. *For an n -dimensional ϕ -concircularly semisymmetric Lorentzian α -Sasakian manifold with respect to the quarter-symmetric non-metric connection, the scalar curvature with respect to the Levi-Civita connection is $n(n-1)\alpha^2 - \alpha\psi^2$.*

Acknowledgement

The authors are grateful to the referees for their valuable suggestions and remarks that definitely improved the paper.

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